

Differentially Algebraic Functions

MS117 Symbolic Combinatorics, SIAM AG23, July 10-14, 2023

Bertrand Teguia Tabuguia

With Rida Ait El Manssour and Anna-Laura Sattelberger

MPI for Mathematics in the Sciences, Leipzig, and MPI for Software Systems, Saarbrücken



July 14, 2023

Some references

-  Ait El Manssour, R., Sattelberger, A.-L., and Teguia Tabuguia, B. (2023).
D-algebraic functions.
arXiv preprint arXiv:2301.02512.
-  Bernardi, O., Bousquet-Mélou, M., and Raschel, K. (2020).
Counting quadrant walks via Tutte's invariant method.
Discrete Mathematics & Theoretical Computer Science.
-  Hong, H., Ovchinnikov, A., Pogudin, G., and Yap, C. (2020).
Global identifiability of differential models.
Communications on Pure and Applied Mathematics, 73(9):1831–1879.
-  Teguia Tabuguia, B. (2023).
Arithmetic of D-algebraic functions.
arXiv preprint arXiv:2305.00702.
-  van Der Hoeven, J. (2019).
Computing with D-algebraic power series.
Applicable Algebra in Engineering, Communication and Computing, 30(1):17–49.

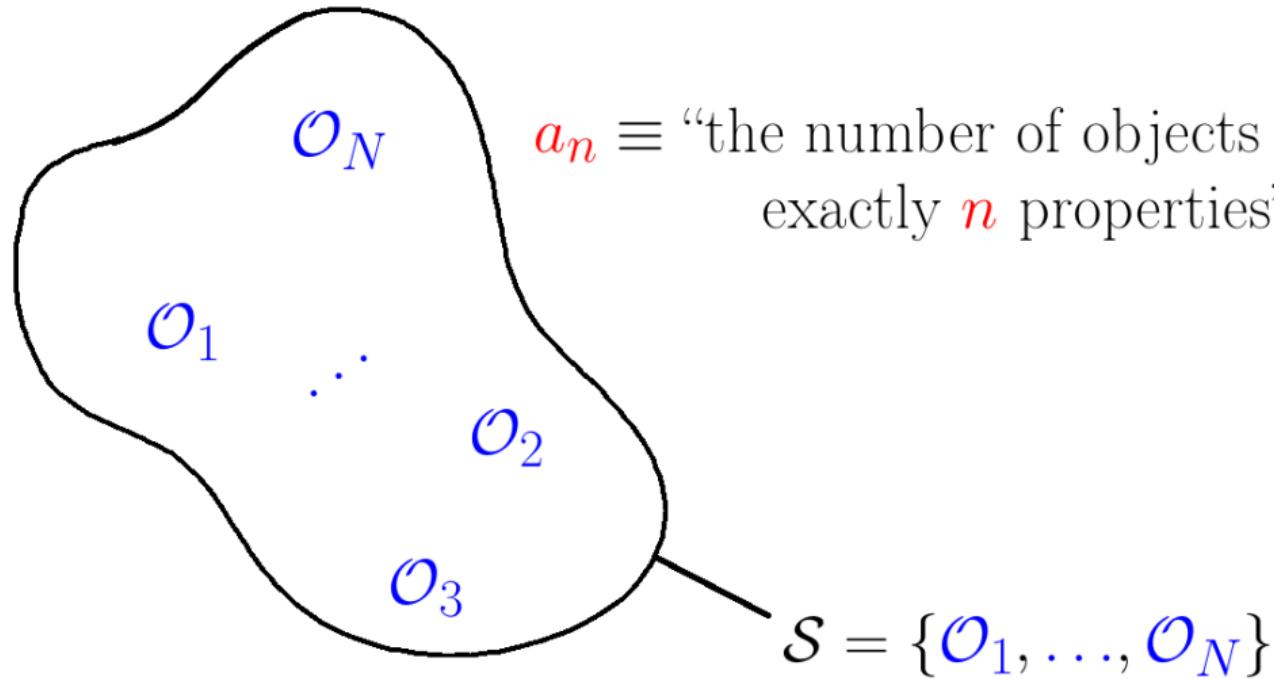
Outline

1. Introduction
2. Arithmetic Operations
3. More Operations and Implementation

1. Introduction

Motivation

Ordinary generating functions may be adapted to finding moments of distributions.



Generating Functions

- ▶ The average number of properties that an object in \mathcal{S} has is $\mu = \frac{1}{N} \sum_{n=1}^{\infty} n a_n$
- ▶ The standard deviation is given by $\sigma = \sqrt{\frac{1}{N} \sum_{n=0}^{\infty} (n - \mu)^2 a_n}$

Generating Functions

- ▶ The average number of properties that an object in \mathcal{S} has is $\mu = \frac{1}{N} \sum_{n=1}^{\infty} n a_n$
- ▶ The standard deviation is given by $\sigma = \sqrt{\frac{1}{N} \sum_{n=0}^{\infty} (n - \mu)^2 a_n}$

If we are lucky enough “**to know**” $f(x) = \sum_{n=0}^{\infty} a_n x^n$. Then we can compute μ and σ by means of operations with f , f' , and f'' .

Generating Functions

- The average number of properties that an object in \mathcal{S} has is $\mu = \frac{1}{N} \sum_{n=1}^{\infty} n a_n$
- The standard deviation is given by $\sigma = \sqrt{\frac{1}{N} \sum_{n=0}^{\infty} (n - \mu)^2 a_n}$

If we are lucky enough “**to know**” $f(x) = \sum_{n=0}^{\infty} a_n x^n$. Then we can compute μ and σ by means of operations with f , f' , and f'' .

Applications of generating functions (H. S. Wilf, Generatingfunctionology, 1990)

- $\mu = \left. \frac{f'(x)}{f(x)} \right|_{x=1}$
- $\sigma = \sqrt{\left. (\log(f(x)))' + (\log(f(x)))'' \right|_{x=1}}$

D-Finite Functions

What is meant by knowing a function?

D-Finite Functions

What is meant by knowing a function?

Holonomic or D-finite representation

$$c_d(x) f^{(d)}(x) + \cdots + c_0(x) f^{(0)}(x) = 0, \quad d \in \mathbb{N}, c_d, \dots, c_0 \in \mathbb{K}[x], c_d \neq 0 \\ f(x_0), \dots, f^{(d-1)}(x_0), x_0 \in \mathbb{K}. \tag{1}$$

In higher dimension, one studies holonomic systems with D -modules techniques
(Satterlberger and Sturmfels, 2019; Koutschan Ph.D. thesis, 2009).

D-Finite Functions

What is meant by knowing a function?

Holonomic or D-finite representation

$$c_d(x) f^{(d)}(x) + \cdots + c_0(x) f^{(0)}(x) = 0, \quad d \in \mathbb{N}, c_d, \dots, c_0 \in \mathbb{K}[x], c_d \neq 0 \\ f(x_0), \dots, f^{(d-1)}(x_0), x_0 \in \mathbb{K}. \quad (1)$$

In higher dimension, one studies holonomic systems with D -modules techniques
(Satterlberger and Sturmfels, 2019; Koutschan Ph.D. thesis, 2009).

Example

- ▶ The Catalan number C_n : $C_3 = 5$: $\textcolor{blue}{((()))} \quad \textcolor{blue}{()()()} \quad \textcolor{blue}{()()0} \quad \textcolor{blue}{()0()0} \quad \textcolor{blue}{0()00}$
$$\frac{1-\sqrt{1-4x}}{2x} = \sum_{n=0}^{\infty} C_n x^n$$
. One can deduce C_n with **FPS**.
- ▶ Manuel Kauers and Peter Paule, The Concrete Tetrahedron, 2011.

D-Finite Functions

What is meant by knowing a function?

Holonomic or D-finite representation

$$c_d(x) f^{(d)}(x) + \cdots + c_0(x) f^{(0)}(x) = 0, \quad d \in \mathbb{N}, c_d, \dots, c_0 \in \mathbb{K}[x], c_d \neq 0 \\ f(x_0), \dots, f^{(d-1)}(x_0), x_0 \in \mathbb{K}. \tag{1}$$

In higher dimension, one studies holonomic systems with D -modules techniques
(Satterlberger and Sturmfels, 2019; Koutschan Ph.D. thesis, 2009).

Example

- ▶ The Catalan number C_n : $C_3 = 5$: $((()))$ $()(())$ $(())()$ $((())()$ $(()())$
 $\frac{1-\sqrt{1-4x}}{2x} = \sum_{n=0}^{\infty} C_n x^n$. One can deduce C_n with **FPS**.
- ▶ Manuel Kauers and Peter Paule, The Concrete Tetrahedron, 2011.
- ▶ If $f := \sin$, then $\log(f)$, $\frac{f'}{f}$ and $(\log(f))''$ are **not** D-finite.

D-Algebraic Functions

“Natural definition”

A function $f := f(x)$ is said to be differentially algebraic (or D-algebraic) if there exist $n \in \mathbb{N}$, and a polynomial $P \in \mathbb{K}[x, y_0, \dots, y_n]$ such that

$$P\left(x, y_0 = f(x), \dots, y_n = f^{(n)}(x)\right) = 0. \quad (2)$$

The differential equation resulting from (2) is called Algebraic Differential Equation (ADE).

We focus on operations with (arbitrary) solutions to ADEs. See [van Der Hoeven, 2019] for initial conditions.

D-Algebraic Functions

“Natural definition”

A function $f := f(x)$ is said to be differentially algebraic (or D-algebraic) if there exist $n \in \mathbb{N}$, and a polynomial $P \in \mathbb{K}[x, y_0, \dots, y_n]$ such that

$$P\left(x, y_0 = f(x), \dots, y_n = f^{(n)}(x)\right) = 0. \quad (2)$$

The differential equation resulting from (2) is called Algebraic Differential Equation (ADE).

We focus on operations with (arbitrary) solutions to ADEs. See [van Der Hoeven, 2019] for initial conditions.

Example

$\log(\sin)$, $\frac{\cos}{\sin}$, and $(\log(\sin))''$ are D-algebraic and satisfy the ADEs

- ▶ $f''(x) + (f'(x))^2 + 1 = 0$,
- ▶ $f'(x) + (f(x))^2 + 1 = 0$, and
- ▶ $(f'(x))^2 + 4(f(x))^3 + 4(f(x))^2 = 0$, respectively.

Operations for D-Algebraic Functions

Theorem

The set \mathcal{A} of D-algebraic functions is a field. Moreover, \mathcal{A} is closed under composition, taking functional inverse, and taking derivatives.

Details proofs can be found in [Ait El Manssour, Sattelberger, and T., 2023]. Other references include [van Der Hoeven, 2019, Bernardi et al., 2020].

Operations for D-Algebraic Functions

Theorem

The set \mathcal{A} of D-algebraic functions is a field. Moreover, \mathcal{A} is closed under composition, taking functional inverse, and taking derivatives.

Details proofs can be found in [Ait El Manssour, Sattelberger, and T., 2023]. Other references include [van Der Hoeven, 2019, Bernardi et al., 2020].

Operations

Let f and g be D-algebraic functions.

- ▶ Binary operations:
 $f \alpha g$, with $\alpha \in \{\times, /, +, -, \circ\}$.
- ▶ Unary operations (only one operand from \mathcal{A}):
 $\alpha(f)$, $\alpha \in \{(\cdot)^n; (\cdot)^{(n)}; (\cdot)^{-1}; R(y)|_{y=}, R \in \mathbb{K}(x, y)\}$.

MathRepo webpage:

<https://mathrepo.mis.mpg.de/DAgebraicFunctions/>

Software presentation of the Maple implementation at ISSAC'23.

2. Arithmetic Operations

Some Differential Algebra

- ▶ Let $R := (\mathbb{K}[x], \frac{d}{dx})$ be a differential ring, $\mathbb{K} \supset \mathbb{Q}$.
- ▶ We call $S_y := R[y, y', \dots, y^{(n)}, \dots]$, $y^{(n)} := \frac{d^n}{dx^n}y$, a “univariate” differential polynomial ring. The variable y and all its derivatives are seen as “one differential variable” called *differential indeterminate*.
- ▶ A differential ideal I , is an ideal $I \in S_y$, that is closed under $\frac{d}{dx}$. For $p_1, \dots, p_k \in S_{y_1, \dots, y_l}$ (multivariate), $I, k \in \mathbb{N}$, we denote by $\langle p_1, \dots, p_k \rangle^{(\infty)}$, the minimal differential ideal containing p_1, \dots, p_k and their derivatives.

Some Differential Algebra

- ▶ Let $R := (\mathbb{K}[x], \frac{d}{dx})$ be a differential ring, $\mathbb{K} \supset \mathbb{Q}$.
- ▶ We call $S_y := R[y, y', \dots, y^{(n)}, \dots]$, $y^{(n)} := \frac{d^n}{dx^n}y$, a “univariate” differential polynomial ring. The variable y and all its derivatives are seen as “one differential variable” called *differential indeterminate*.
- ▶ A differential ideal I , is an ideal $I \in S_y$, that is closed under $\frac{d}{dx}$. For $p_1, \dots, p_k \in S_{y_1, \dots, y_l}$ (multivariate), $l, k \in \mathbb{N}$, we denote by $\langle p_1, \dots, p_k \rangle^{(\infty)}$, the minimal differential ideal containing p_1, \dots, p_k and their derivatives.

Definition (D-algebraic function)

A function $f := f(x)$ is D-algebraic with respect to x , say $f \in \mathcal{A}_x$, if there exists $P \in S_y$, such that $P(y = f(x)) = 0$.

Some Differential Algebra

- ▶ Let $R := (\mathbb{K}[x], \frac{d}{dx})$ be a differential ring, $\mathbb{K} \supset \mathbb{Q}$.
- ▶ We call $S_y := R[y, y', \dots, y^{(n)}, \dots]$, $y^{(n)} := \frac{d^n}{dx^n}y$, a “univariate” differential polynomial ring. The variable y and all its derivatives are seen as “one differential variable” called *differential indeterminate*.
- ▶ A differential ideal I , is an ideal $I \in S_y$, that is closed under $\frac{d}{dx}$. For $p_1, \dots, p_k \in S_{y_1, \dots, y_l}$ (multivariate), $I, k \in \mathbb{N}$, we denote by $\langle p_1, \dots, p_k \rangle^{(\infty)}$, the minimal differential ideal containing p_1, \dots, p_k and their derivatives.

Definition (D-algebraic function)

A function $f := f(x)$ is D-algebraic with respect to x , say $f \in \mathcal{A}_x$, if there exists $P \in S_y$, such that $P(y = f(x)) = 0$.

For convenience, we use different differential indeterminates for distinct D-algebraic functions:

For $f, g \in \mathcal{A}_x$, we consider $P \in S_{y_1}, Q \in S_{y_2}, P(y_1 = f(x)) = Q(y_2 = g(x)) = 0$.

Note: $P, Q \in S_{y_1, y_2}$.

Differential elimination

By arithmetic operations we mean $\alpha \in \{\times, /, +, -\}$.

Differential elimination

By arithmetic operations we mean $\alpha \in \{\times, /, +, -\}$.

- ▶ Let $f := f(x)$, and $g := g(x)$ be in \mathcal{A}_x
- ▶ We have $P(y_1 = f(x)) = 0$, $P \in S_{y_1}$, and $Q(y_2 = g(x)) = 0$, $Q \in S_{y_2}$.

Differential elimination

By arithmetic operations we mean $\alpha \in \{\times, /, +, -\}$.

- ▶ Let $f := f(x)$, and $g := g(x)$ be in \mathcal{A}_x
- ▶ We have $P(y_1 = f(x)) = 0$, $P \in S_{y_1}$, and $Q(y_2 = g(x)) = 0$, $Q \in S_{y_2}$.
- ▶ We want $T \in S_z$, such that $T(z = (f \alpha g)(x)) = 0$.

Differential elimination

By arithmetic operations we mean $\alpha \in \{\times, /, +, -\}$.

- ▶ Let $f := f(x)$, and $g := g(x)$ be in \mathcal{A}_x
- ▶ We have $P(y_1 = f(x)) = 0$, $P \in S_{y_1}$, and $Q(y_2 = g(x)) = 0$, $Q \in S_{y_2}$.
- ▶ We want $T \in S_z$, such that $T(z = (f\alpha g)(x)) = 0$.
- ▶ We work on $S_{y_1, y_2, z}$. Let r be the numerator of $z - y_1\alpha y_2$, and consider the differential ideal

$$I_{P, Q, r} := \langle P, Q, r \rangle^{(\infty)} \subset S_{y_1, y_2, z}. \quad (3)$$

Differential elimination

By arithmetic operations we mean $\alpha \in \{\times, /, +, -\}$.

- ▶ Let $f := f(x)$, and $g := g(x)$ be in \mathcal{A}_x
- ▶ We have $P(y_1 = f(x)) = 0$, $P \in S_{y_1}$, and $Q(y_2 = g(x)) = 0$, $Q \in S_{y_2}$.
- ▶ We want $T \in S_z$, such that $T(z = (f\alpha g)(x)) = 0$.
- ▶ We work on $S_{y_1, y_2, z}$. Let r be the numerator of $z - y_1\alpha y_2$, and consider the differential ideal

$$I_{P, Q, r} := \langle P, Q, r \rangle^{(\infty)} \subset S_{y_1, y_2, z}. \quad (3)$$

- ▶ **Main Goal:** eliminate the differential indeterminates y_1 and y_2 .

Differential elimination

By arithmetic operations we mean $\alpha \in \{\times, /, +, -\}$.

- ▶ Let $f := f(x)$, and $g := g(x)$ be in \mathcal{A}_x
- ▶ We have $P(y_1 = f(x)) = 0$, $P \in S_{y_1}$, and $Q(y_2 = g(x)) = 0$, $Q \in S_{y_2}$.
- ▶ We want $T \in S_z$, such that $T(z = (f \alpha g)(x)) = 0$.
- ▶ We work on $S_{y_1, y_2, z}$. Let r be the numerator of $z - y_1 \alpha y_2$, and consider the differential ideal

$$I_{P, Q, r} := \langle P, Q, r \rangle^{(\infty)} \subset S_{y_1, y_2, z}. \quad (3)$$

- ▶ **Main Goal:** eliminate the differential indeterminates y_1 and y_2 .

Theorem (Ritt-Raudenbach)

Let I be a differential ideal in S_y . The radical ideal \sqrt{I} is a differential ideal, and moreover, there exist prime differential ideals I_1, \dots, I_m such that

$$\sqrt{I} = I_1 \cap I_2 \cap \cdots \cap I_m \quad (4)$$

Method I

We want to find a differential polynomial

$$T \in I_{P,Q,r} \cap S_z$$

Method I

We want to find a differential polynomial

$$T \in I_{P,Q,r} \cap S_z \neq \{0\}$$

Method I

We want to find a differential polynomial

$$T \in I_{P,Q,r} \cap S_z \neq \{0\}$$

Method I

1. For $N \in \mathbb{N}$, let $I_{P,Q,r}^{(\leq N)}$ be the algebraic ideal defined by P, Q, r and their first N derivatives, and $S_z^{(\leq N)} := \mathbb{K}[x][z, z', \dots, z^{(N)}]$ (a polynomial ring).

Method I

We want to find a differential polynomial

$$T \in I_{P,Q,r} \cap S_z \neq \{0\}$$

Method I

1. For $N \in \mathbb{N}$, let $I_{P,Q,r}^{(\leq N)}$ be the algebraic ideal defined by P, Q, r and their first N derivatives, and $S_z^{(\leq N)} := \mathbb{K}[x][z, z', \dots, z^{(N)}]$ (a polynomial ring).
2. Use Gröbner bases to iterate the computations

$$N \leftarrow N + 1; \tag{5}$$

$$J \leftarrow I_{P,Q,r}^{(\leq N)} \cap S_z^{(\leq N)}. \tag{6}$$

3. Until $J \neq \{0\}$.
4. Return $T \in J$, such that T has minimum degree among the generators of the minimal order in J .

Method I

We want to find a differential polynomial

$$T \in I_{P,Q,r} \cap S_z \neq \{0\}$$

Method I

1. For $N \in \mathbb{N}$, let $I_{P,Q,r}^{(\leq N)}$ be the algebraic ideal defined by P, Q, r and their first N derivatives, and $S_z^{(\leq N)} := \mathbb{K}[x][z, z', \dots, z^{(N)}]$ (a polynomial ring).
2. Use Gröbner bases to iterate the computations

$$N \leftarrow N + 1; \tag{5}$$

$$J \leftarrow I_{P,Q,r}^{(\leq N)} \cap S_z^{(\leq N)}. \tag{6}$$

3. Until $J \neq \{0\}$.
4. Return $T \in J$, such that T has minimum degree among the generators of the minimal order in J .

Questions: how many times do we need to iterate? What can we say about the order?

Dynamical system

Consider $S_{\mathbf{y}, z}$, where $\mathbf{y} = (y_1, \dots, y_n)$, and the dynamical system

$$\begin{cases} \mathbf{y}' = \mathbf{A}(\mathbf{y}) \\ z = B(\mathbf{y}) \end{cases}, \quad (\mathcal{M})$$

where $\mathbf{A} = (A_1, \dots, A_n) \in \mathbb{K}(x)(y_1, \dots, y_n)^n$, $B \in \mathbb{K}(x)(y_1, \dots, y_n)$.

Dynamical system

Consider $S_{\mathbf{y},z}$, where $\mathbf{y} = (y_1, \dots, y_n)$, and the dynamical system

$$\begin{cases} \mathbf{y}' = \mathbf{A}(\mathbf{y}) \\ z = B(\mathbf{y}) \end{cases}, \quad (\mathcal{M})$$

where $\mathbf{A} = (A_1, \dots, A_n) \in \mathbb{K}(x)(y_1, \dots, y_n)^n$, $B \in \mathbb{K}(x)(y_1, \dots, y_n)$.

Differential ideal associated to (\mathcal{M})

Let $Q := \text{lcm}(\text{denominators in } \mathcal{M})$, $A_i = a_i/Q$, $i = 1, \dots, n$, $B = b/Q$, and

$$I_{\mathcal{M}} := \langle Q\mathbf{y}' - \mathbf{a}(y), Qz - b(\mathbf{y}) \rangle : Q^\infty \subset S_{\mathbf{y},z}, \quad (7)$$

$$I_{\mathcal{M}}^{(\leq j)} := \langle (Q\mathbf{y}' - \mathbf{a}(y))^{(<j)}, (Qz - b(\mathbf{y}))^{\leq j} \rangle \subset S_{\mathbf{y},z}^{(\leq j)} \quad (8)$$

Dynamical system

Consider $S_{\mathbf{y},z}$, where $\mathbf{y} = (y_1, \dots, y_n)$, and the dynamical system

$$\begin{cases} \mathbf{y}' = \mathbf{A}(\mathbf{y}) \\ z = B(\mathbf{y}) \end{cases}, \quad (\mathcal{M})$$

where $\mathbf{A} = (A_1, \dots, A_n) \in \mathbb{K}(x)(y_1, \dots, y_n)^n$, $B \in \mathbb{K}(x)(y_1, \dots, y_n)$.

Differential ideal associated to (\mathcal{M})

Let $Q := \text{lcm}(\text{denominators in } \mathcal{M})$, $A_i = a_i/Q$, $i = 1, \dots, n$, $B = b/Q$, and

$$I_{\mathcal{M}} := \langle Q\mathbf{y}' - \mathbf{a}(y), Qz - b(\mathbf{y}) \rangle : Q^\infty \subset S_{\mathbf{y},z}, \quad (7)$$

$$I_{\mathcal{M}}^{(\leq j)} := \langle (Q\mathbf{y}' - \mathbf{a}(y))^{(<j)}, (Qz - b(\mathbf{y}))^{\leq j} \rangle \subset S_{\mathbf{y},z}^{(\leq j)} \quad (8)$$

[Hong, Ovchinnikov, Pogudin, and Yap, 2020]

$$I_{\mathcal{M}}^{(\leq \textcolor{blue}{n})} \cap S_z^{(\leq \textcolor{blue}{n})} \neq \{0\} \quad (9)$$

Method II

Computing ADEs from dynamical systems

1. Let

$$P := P(y_1, \dots, y_1^{(n_1)}), \quad Q := Q(y_2, \dots, y_2^{(n_2)}), \quad (10)$$

and assume $\deg_{y_1^{(n_1)}}(P) = \deg_{y_2^{(n_2)}}(Q) = 1$.

Method II

Computing ADEs from dynamical systems

1. Let

$$P := P(y_1, \dots, y_1^{(n_1)}), \quad Q := Q(y_2, \dots, y_2^{(n_2)}), \quad (10)$$

and assume $\deg_{y_1^{(n_1)}}(P) = \deg_{y_2^{(n_2)}}(Q) = 1$.

2. Consider the differential indeterminates $w_1, \dots, w_{n_1+n_2}$, such that

$$w_1 := y_1, \dots, w_{n_1} := y_1^{(n_1-1)}, w_{n_1+1} := y_2, \dots, w_{n_1+n_2} := y_2^{(n_2-1)} \quad (11)$$

Method II

Computing ADEs from dynamical systems

1. Let

$$P := P(y_1, \dots, y_1^{(n_1)}), \quad Q := Q(y_2, \dots, y_2^{(n_2)}), \quad (10)$$

and assume $\deg_{y_1^{(n_1)}}(P) = \deg_{y_2^{(n_2)}}(Q) = 1$.

2. Consider the differential indeterminates $w_1, \dots, w_{n_1+n_2}$, such that

$$w_1 := y_1, \dots, w_{n_1} := y_1^{(n_1-1)}, w_{n_1+1} := y_2, \dots, w_{n_1+n_2} := y_2^{(n_2-1)} \quad (11)$$

3. Deduce the ADE sought from the dynamical system

$$\begin{cases} w'_1 = w_2 \\ \dots \\ w'_{n_1} = r_P(w_1, \dots, w_{n_1-1}), \quad r_P := \text{Solve}(P, y_1^{(n_1)}) \\ \dots \\ w'_{n_1+n_2} = r_Q(w_{n_1+1}, \dots, w_{n_1+n_2-1}), \quad r_Q := \text{Solve}(Q, y_2^{(n_2)}) \\ z = w_1 \alpha w_{n_1+1} \end{cases} . \quad (12)$$

Examples

- $f(x) := \exp(x)$, $P := y'_1 - y_1$; and $g(x) := \log(x)$, $Q(x) := x y'_2 - 1$. Find T such that
$$T \left(z(x) = \frac{f(x)}{g(x)} \right) = 0.$$
- We find

$$T := x z'' z - 2 x z'^2 + (2x + 1) z' z - (x + 1) z^2$$

Examples

- $f(x) := \exp(x)$, $P := y'_1 - y_1$; and $g(x) := \log(x)$, $Q(x) := x y'_2 - 1$. Find T such that $T\left(z(x) = \frac{f(x)}{g(x)}\right) = 0$.
- We find

$$T := x z'' z - 2 x z'^2 + (2x + 1) z' z - (x + 1) z^2$$

- $P := y''_1 + y'^2_1$ and $Q := y'_2 - y^2_2$. Find T : $T(z(x) = f(x) + g(x)) = 0$, where $P(f) = Q(g) = 0$.
- We find

$$\begin{aligned} T := & 336 z' z''^2 z^{(3)2} + 1024 z'^9 + 432 z'^8 - 96 z'^3 z'' z^{(3)2} \\ & - 384 z' z'' z^{(3)2} - 576 z'^2 z''^2 z^{(3)} + 768 z' z''^3 z^{(3)} + 672 z'^2 z''^3 z^{(3)} \\ & - 1536 z'^3 z''^2 z^{(3)} - 1152 z'^5 z'' z^{(3)} - 32 z^{(3)3} - 16 z''^6 - 288 z''^5 \\ & + 288 z''^3 z^{(3)} + 24 z''^2 z^{(3)2} - 1008 z'^2 z'' z^{(3)2} + 432 z''^4 + 24 z'' z^{(3)3} \\ & - 768 z'^6 z''^2 + 4608 z'^3 z''^3 + 4224 z'^7 z'' + 1728 z'^6 z'' + 6336 z'^5 z''^2 \\ & - 672 z'^4 z''^3 + 192 z'^3 z''^4 + 2592 z'^4 z''^2 - 456 z'^4 z^{(3)2} + 576 z'^2 z''^4 \\ & - 384 z' z''^5 - 192 z'^3 z^{(3)2} + 1728 z'^2 z''^3 - 48 z'^2 z^{(3)3} + 1728 z''^4 z' \\ & - 192 z''^4 z^{(3)} - 8 z''^3 z^{(3)2} - 96 z' z^{(3)3} - z^{(3)4} - 480 z'^4 z'' z^{(3)}. \end{aligned} \tag{13}$$

Related work

- Jiménez-Pastor, A., Pillwein, V., Singer, M., 2020. Some structural results on D^n -finite functions. *Advances in Applied Mathematics* 117, ID 102027 (29 pages).

Related work

- ▶ Jiménez-Pastor, A., Pillwein, V., Singer, M., 2020. Some structural results on D^n -finite functions. *Advances in Applied Mathematics* 117, ID 102027 (29 pages).
- ▶ Boulier, F., Lazard, D., Ollivier, F., Petitot, M., 1995. Representation for the radical of a finitely generated differential ideal. In ISSAC'95: Proceedings of the 1995 International Symposium on Symbolic and Algebraic Computation. ACM Press, New York, NY, USA, pp. 158–166.

Related work

- ▶ Jiménez-Pastor, A., Pillwein, V., Singer, M., 2020. Some structural results on D^n -finite functions. *Advances in Applied Mathematics* 117, ID 102027 (29 pages).
- ▶ Boulier, F., Lazard, D., Ollivier, F., Petitot, M., 1995. Representation for the radical of a finitely generated differential ideal. In ISSAC'95: Proceedings of the 1995 International Symposium on Symbolic and Algebraic Computation. ACM Press, New York, NY, USA, pp. 158–166.
- ▶ Bächler, T., Gerdt, V., Lange-Hegermann, M., Robertz, D., 2012. Algorithmic Thomas decomposition of algebraic and differential systems. *Journal of Symbolic Computation* 47, 1233–1266.
- ▶ Robertz, D., 2014. Thomas Decomposition of Differential Systems. In Robertz, D., 2014. Formal Algorithmic Elimination for PDEs. Springer 2121. Switzerland. Section 2.2.

Related work

Improved Method II [T., 2023]

- ▶ Example: $P_1 := y_1'^2 + y_1^2 - 1, P_2 := y_2' - y_2, P_3 := y_3'^3 + y_3'^2 + 3$
- ▶ Find a third-order differential polynomial T : $T \left(z(x) = \frac{f_1(x) f_3(x)}{f_2(x)} \right)$, where $P_1(f_1) = P_2(f_2) = P_3(f_3) = 0$.

Related work

Improved Method II [T., 2023]

- ▶ Example: $P_1 := y_1'^2 + y_1^2 - 1, P_2 := y_2' - y_2, P_3 := y_3'^3 + y_3'^2 + 3$
- ▶ Find a third-order differential polynomial T : $T \left(z(x) = \frac{f_1(x) f_3(x)}{f_2(x)} \right)$, where $P_1(f_1) = P_2(f_2) = P_3(f_3) = 0$.
- ▶ We find

$$T := \left(z'' + 2z' + z \right) \left(z'' + 2z' + 2z \right)^2 \left(12z^2 + 32z'z + 20z''z + 6z^{(3)}z + 24z'^2 + 30z''z' + 10z^{(3)}z' + 9z''^2 + 6z^{(3)}z'' + z^{(3)2} \right) \quad (14)$$

These non-“l.h.o.” cases are often well handled by this approach.

3. More Operations and Implementation

Composition

The main idea

- ▶ Let $f, g \in \mathcal{A}_x$, $P := P(y_1, \dots, y_1^{(n_1)})$, $Q := Q(y_2, \dots, y_2^{(n_2)})$, $P(f) = Q(g) = 0$.
- ▶ How to find $T \in S_z$, $T(z = f \circ g) = 0$?

Composition

The main idea

- ▶ Let $f, g \in \mathcal{A}_x$, $P := P(y_1, \dots, y_1^{(n_1)})$, $Q := Q(y_2, \dots, y_2^{(n_2)})$, $P(f) = Q(g) = 0$.
- ▶ How to find $T \in S_z$, $T(z = f \circ g) = 0$?
- ▶ Observation:

$$\begin{aligned}(f(g))' &= g' f'(g), \\ (f(g))'' &= g'' f'(g) + g'^2 f''(g), \\ (f(g))^{(3)} &= g^{(3)} f'(g) + g'' g' f''(g) + g'^3 f^{(3)}(g) \\ &\quad \dots\end{aligned}\tag{15}$$

Hence a linear system in y_1 with coefficients in terms of z and y_2 .

Composition

The main idea

- ▶ Let $f, g \in \mathcal{A}_x$, $P := P(y_1, \dots, y_1^{(n_1)})$, $Q := Q(y_2, \dots, y_2^{(n_2)})$, $P(f) = Q(g) = 0$.
- ▶ How to find $T \in S_z$, $T(z = f \circ g) = 0$?
- ▶ Observation:

$$\begin{aligned}(f(g))' &= g' f'(g), \\ (f(g))'' &= g'' f'(g) + g'^2 f''(g), \\ (f(g))^{(3)} &= g^{(3)} f'(g) + g'' g' f''(g) + g'^3 f^{(3)}(g) \\ &\quad \dots\end{aligned}\tag{15}$$

Hence a linear system in y_1 with coefficients in terms of z and y_2 .

- ▶ Elimination of y_1 by linear algebra.
- ▶ Proceed by constructing a dynamical system of dimension $n_1 + n_2$, and deduce the ADE sought.

Implementation in Macaulay2 and Maple

- ▶ <https://mathrepo.mis.mpg.de/DAlgebraicFunctions/>
- ▶ <https://mathrepo.mis.mpg.de/OperationsForDAlgebraicFunctions/>

Implementation in Macaulay2 and Maple

- ▶ <https://mathrepo.mis.mpg.de/DAlgebraicFunctions/>
- ▶ <https://mathrepo.mis.mpg.de/OperationsForDAlgebraicFunctions/>

The NLDE Package

NonLinear algebra and Differential Equations (or **NonLinear Differential Equations**).

1. Univariate arithmetic: `NLDE:-arithmeticDalg`, `NLDE:-unaryDalg`;
2. Multivariate arithmetic: `NLDE:-MDalg`: `MDalg:-arithmeticMDalg`;
3. Composition: `NLDE:-composeDalg`;
4. Functional inverse: `NLDE:-invDalg`;
5. Differentiation: `NLDE:-diffDalg`;
6. Ansatz approach for univariate arithmetic (δ_k -finite functions): `NLDE:-AnsatzDalg`:
`AnsatzDalg:-arithmeticDeltak`, `AnsatzDalg:-unaryDeltak`.

The NLDE Package

Example (Arithmetic)

```
> ADE1:=diff(y1(x),x)^3+y1(x)+1=0:
```

```
> ADE2:=diff(y2(x),x)^2-y2(x)-1=0:
```

```
> NLDE:=arithmeticDalg([ADE1,ADE2],[y1(x),y2(x)],z=y1+y2)
```

$$-24 \left(\frac{d^2}{dx^2} z(x) \right)^3 + 36 \left(\frac{d^2}{dx^2} z(x) \right)^2 - 18 \frac{d^2}{dx^2} z(x) + 8 \frac{d^3}{dx^3} z(x) + 3 = 0 \quad (16)$$

```
> Res:=NLDE:=arithmeticDalg([ADE1,ADE2],[y1(x),y2(x)],z=y1+y2,lho=false):
```

$$\begin{aligned} & \left(\left(\frac{d}{dx} z(x) \right)^3 + z(x) + 2 \right) \left(\left(\frac{d}{dx} z(x) \right)^2 - z(x) - 2 \right) \left(216 \left(\frac{d}{dx} z(x) \right)^2 \left(\frac{d^2}{dx^2} z(x) \right)^3 - 216 z(x) \left(\frac{d^2}{dx^2} z(x) \right)^3 \right. \\ & - 324 \left(\frac{d}{dx} z(x) \right)^2 \left(\frac{d^2}{dx^2} z(x) \right)^2 - 432 \left(\frac{d^2}{dx^2} z(x) \right)^3 + 144 \left(\frac{d}{dx} z(x) \right) \left(\frac{d^2}{dx^2} z(x) \right)^2 + 324 z(x) \left(\frac{d^2}{dx^2} z(x) \right)^2 \\ & + 162 \left(\frac{d}{dx} z(x) \right)^2 \left(\frac{d^2}{dx^2} z(x) \right) + 648 \left(\frac{d^2}{dx^2} z(x) \right)^2 - 144 \left(\frac{d}{dx} z(x) \right) \left(\frac{d^2}{dx^2} z(x) \right) - 162 z(x) \left(\frac{d^2}{dx^2} z(x) \right) \\ & \left. - 27 \left(\frac{d}{dx} z(x) \right)^2 - 300 \frac{d^2}{dx^2} z(x) + 36 \frac{d}{dx} z(x) + 27 z(x) + 50 \right) = 0 \end{aligned} \quad (17)$$

The NLDE Package

Example (Composition)

The exponential of the Painlevé transcendent of type I.

```
> ADE1 := diff(y1(x), x) - y1(x) = 0:  
> ADE2 := diff(y2(x), x, x)=6*y2(x)^2+x: #the transcendent  
> NLDE:=composeDalg([ADE1,ADE2], [y1(x),y2(x)], z(x))  

$$\begin{aligned} & 24x \left( \frac{d}{dx}z(x) \right)^2 z(x)^4 + z(x)^6 - 2z(x)^5 \left( \frac{d^3}{dx^3}z(x) \right) + 6 \left( \frac{d^2}{dx^2}z(x) \right) \left( \frac{d}{dx}z(x) \right) z(x)^4 \\ & + \left( \frac{d^3}{dx^3}z(x) \right)^2 z(x)^4 - 4 \left( \frac{d}{dx}z(x) \right)^3 z(x)^3 - 24 \left( \frac{d^2}{dx^2}z(x) \right) \left( \frac{d}{dx}z(x) \right)^2 z(x)^3 \\ & - 6 \left( \frac{d^3}{dx^3}z(x) \right) \left( \frac{d^2}{dx^2}z(x) \right) \left( \frac{d}{dx}z(x) \right) z(x)^3 + 24 \left( \frac{d}{dx}z(x) \right)^4 z(x)^2 \\ & + 4 \left( \frac{d^3}{dx^3}z(x) \right) \left( \frac{d}{dx}z(x) \right)^3 z(x)^2 + 9z(x)^2 \left( \frac{d}{dx}z(x) \right)^2 \left( \frac{d^2}{dx^2}z(x) \right)^2 \\ & - 12z(x) \left( \frac{d}{dx}z(x) \right)^4 \left( \frac{d^2}{dx^2}z(x) \right) + 4 \left( \frac{d}{dx}z(x) \right)^6 = 0 \end{aligned} \tag{18}$$

```

The NLDE Package

Example (Functional Inverse)

Functional inverse of the Weierstrass elliptic function \wp .

```
> ADE:=diff(y(x),x)^2=4*y(x)^3-g2*y(x)-g3:  
> invDalg(ADE,y(x),z(x))
```

$$1 + \left(-4x^3 + g_2 x + g_3 \right) \left(\frac{d}{dx} z(x) \right)^2 = 0. \quad (19)$$

Take away. Note that:

- ▶ Every rational expression of D-algebraic functions satisfies a **computable** ADE of order at most the **sum of the orders** of the ADEs defining those D-algebraic functions.
- ▶ The composition of two D-algebraic functions is a D-algebraic function that fulfils a **computable** ADE whose order is at most the **sum of the orders** of the two defining ADEs.
- ▶ The derivative of a D-algebraic function is a D-algebraic function satisfying a **computable** ADE of the **same order** as the ADE defining the given function.
- ▶ The functional inverse of a D-algebraic function is a D-algebraic function that fulfils a **computable** ADE of the **same order** as the ADE defining the given function.

If $\wp(x)$ satisfies

$$y'(x)^2 = 4y(x)^3 - g_2 y(x) - g_3.$$

Then the functional inverse \wp^{-1} of \wp satisfies

$$1 + \left(-4x^3 + g_2x + g_3\right) y'(x)^2 = 0.$$

See more about NLDE at <https://mathrepo.mis.mpg.de/OperationsForDAlgebraicFunctions/>

Thank You!